

	Place	09:00	10:00	11:00	12:00	13:00	14:00	15:00	16:00	17:00	18:00	19:00	20:00
Mo	FEI STU D424	Opening, Sigurd Skogestad, Self-optimizing control I., Discussion				Lunch	Vesely, Rosinová, Tuan, Huba, Ľapák, Bisták: Robust, Nonlinear and Constrained Control			Excursion FEI STU	Coctail		
Tu	FCHPT STU 641	Ramprasad Yelchuru, Sigurd Skogestad Self-optimizing control II.		Morten Hovd: I, II, III		Lunch	Fikar et al. Complexity Reduction in MPC						
We	SjF STU	Steering Committee Meeting, Tor Arne.: Moving Horizon Estimation, Discussion group				Lunch	Rohal et al. Predictive control of Mechatronic Systems						
Th	FEI STU D424	Johannes Jaschke, Sigurd Skogestad Self-optimizing control III		Arnfinn Aas Eilsen: Nano-positioning estimation and control, Discussion		Lunch	Excercises on demand (individual choice) - STU FEI/FME/ FCHEFP				Banquet		
Fr	FEI STU D424	Francesco Scibilia I, II		Selvanathan Sivalingam I		Lunch	Selvanathan Final Discussion, Free Sivalingam II programme						

FCHPT Faculty of Chemical and Food Technology Radlinskeho 11
FME Faculty of Mechanical Eng. Mytna ul.
FEI Faculty of Electrical Eng. and Information Technology Ilkovicova 3

"Self-optimizing control", part I Optimal measurement combinations based on convex formulations; II MIQP formulations for structured problems; III Nonlinear combinations of polynomial systems

M. Hovd: I Patchy approximate explicit control; II Penalty function design for MPC controllers; III Piecewise quadratic Lyapunov functions for piecewise linear and piecewise affine systems

F. Scibilia: I Feasible Sets for linear MPC and their Approximations; II Robust Feasibility for Constrained Linear Systems Controlled by PWA Feedback Laws

S. Sivalingam: I Frequency domain approaches to controller performance monitoring; II Multivariate time delay estimation
Fikar et al: Complexity reduction I, II (Fikar), III (Rauová), MPT Toolbox (Kvasnica)